| Check | Fault Code | Monitoring Strategy | Malfunction Criteria | Threshold Value | Secondary Parameters | Enable Conditions | Time Required | MIL Illumination |
|---------------------|-----------------------|--------------------------|---|----------------------------|---|---------------------|---------------|------------------|
| Shift solenoid 1 | P0973 | circuit continuity | Comparison of TCM output signal and monitoring leve | (GND short) | DS_Active_EG_V | TRUE | 0.3sec | 1D.C. |
| (GND short) | | | | Monitoring signal is Low a | t Emergency mode | No | | |
| Shift solenoid 1 | P0974 | circuit continuity | | output ON | _ | | 0.5sec | 1D.C. |
| (+B short, Open) | | | _ | (+B short / Open) | | | | 15.0 |
| Shift solenoid 2 | P0976 | circuit continuity | | Wonitoring signal is High | | | 03sec | 1D.C. |
| (GND short) | B 4 4 F | | | output OFF | | | | 12.0 |
| Shift solenoid 2 | P0977 | circuit continuity | | | | | 0.5sec | 1D.C. |
| (+B snort, Open) | D0070 | | - | | | | | 10.0 |
| Shift solenoid 3 | P0979 | circuit continuity | | | | | 0.3sec | 1D.C. |
| (GND short) | Doogo | stand to a set to site . | - | | | | 0.5 | 10.0 |
| Shift solenoid 3 | P0980 | circuit continuity | | | | | U.SSEC | 1D.C. |
| (+B snort, Open) | Dooco | | | (CND short Open) | | TDUE | 40.5 | 10.0 |
| Linear solenoid SLI | P0962 | circuit continuity | Check the feedback current value | (GND short, Open) | DS_ACTIVE_EG_V | IRUE | 12.5Sec | 1D.C. |
| (GND snort, Open) | Dooco | | | <=00 (I.B.Short) | Emergency mode | | 0.5 | 10.0 |
| Linear solenoid SLI | P0963 | circuit continuity | | (+B 31011) | DS_Active_EG_V | IRUE | 0.5Sec | 1D.C. |
| (+B Short) | | | | >=1000 | Emergency mode | N0 | - | |
| | | | | | Pass time from no failure detection at | >= TSEC | | |
| Linear colonaid CLU | DOOCC | oirouit continuitu | - | | | TRUE | 10 5000 | 10.0 |
| (CND Short/Onen) | P0966 | circuit continuity | | | DS_ACIIVE_EG_V | IRUE | 12.5Sec | ID.C. |
| (GND Short/Open) | DOOGZ | oireuit continuitu | | | Emergency mode | | 0.5000 | 10.0 |
| Linear solenoid SLU | P0967 | circuit continuity | | | DS_ACIIVE_EG_V | IRUE | 0.5sec | ID.C. |
| | | | | | Bass time from no foilure detection at | NO > = 1000 | - | |
| | | | | | Pass time from no failure detection at | >= TSEC | | |
| Linear colonaid CLU | DOOGE | oireuit continuitu | | [Critorion1] | | TRUE | [Critorian4] | 10.0 |
| (Terminal Short) | P0965 | circuit continuity | | | DS_Active_EG_V | IRUE | | 1D.C. |
| (Terminal Short) | | | | >8011A | Emergency mode | No | Z.75Sec | |
| | | | (enor current value : | | During Shill Better weltere | NU | - | |
| | | | | [Critorion2] | Dallery vollage | | [Criterien 2] | |
| | | | [Criterion2] | | | >= 20°C | [Chimes | |
| | | | Thermal Shut Down of Linear Sciencid Driver | Occurrence | | Not fail | oumes | |
| | | | | | (P0/11, P0/12, P0/13) | . 052mA | - | |
| | | | | | SLU current | | - | |
| Linear colonaid CLU | D0744 | functional sheets | Follure is detected if the following condition is | >-2000 | SLO larger current value | | China a a | 10.0 |
| | P0741 | Tunctional check | Pailure is detected if the following condition is | >=2360 | DS_ACIIVE_EG_V | IRUE | oumes | ID.C. |
| (OFF Sluck) | | | Salislieu. | >=100rpm | Time after geer celecter change to D. 2 | NU > 8000 | - | |
| | | | - Engine revolution - Input revolution | >=100ipiii | range defined | >osec | | |
| | | | | | During chift | No | - | |
| | | | | | Time offer shift shange | NO | - | |
| | | | | | Time after look up ON output | > 2000 | - | |
| | | | | | | >2580 | - | |
| | | | | | Oil temperature | >=200 | - | |
| | | | | | Throttlo | >=15% | - | |
| | | | | | Input revolution | >=15% | - | |
| | | | | | Engine torque | >=1501pm, <=60001pm | - | |
| | | | | | Engine torque | >2000rpm | - | |
| | | | | | Shift solopoid | >2000pm | - | |
| | | | | | | Not fall | | |
| | | | | | (31. F0973,F0974 | - | | |
| | | | | | 52. FU970,FU977 | 4 | | |
| | | | | | S3. F0979,F0960 | _ | | |
| | | | | | SLI. 10902, F0903 | 4 | | |
| | | | | 1 | | 4 | | |
| | | | | | Input revolution sensor(P0722) | - | | |
| | | | | | Selector position switch(P0717) | 4 | | |
| | | | | | Oil temperature senser | 4 | | |
| | | | | | | | | |
| | 1 | 1 | | 1 | (FU/11, PU/12, PU/13) | 1 | 1 | |

| Check | Fault Code | Monitoring Strategy | Malfunction Criteria | Threshold Value | Secondary Parameters | Enable Conditions | Time Required | MIL Illumination |
|--|------------|---------------------|---|----------------------------|--|---|---------------|------------------|
| | | | | | Engine torque signal(P2637) | | | |
| | | | | | Throttle signal(P1125) | | | |
| Output revolution sense | P0722 | circuit continuity | Check the output revolution pulse while detectinc | No pulse | DS Active EG V | TRUE | 500times | 1D.C. |
| | | | input revolution sensor signal 10 pulse. | | Time after gear selector change from P, R or N range to others (at oil temp >=20deg.C and oil temp sensor is no failure(P0711,P0712,P0713 or Vehicle Speed calculated by output revolution sensor >= 66 km/b) | >=10sec (>=2.5sec)) | | |
| | | | | | Selector position switch | Defined | _ | |
| | | | | | Vehicle speed | Denned > 7 km/h (1st Gear) > 13 km/h (2nd Gear) > 18 km/h (3rd Gear) > 26 km/h (4th Gear) | | |
| | | | | | Shift solenoid (S1: P0973,P0974 S2: P0976,P0977 S3: P0979,P0980) Selector position switch(P0705) | Not fail | | |
| Input revolution sensor | P0717 | circuit continuity | Check the input revolution pulse while detecting | No pulse | DS Active EG V | TRUE | 500times | 1D C |
| | | | output revolution sensor signal 6 pulse. | | P, R or N range to others (at oil temp >=20deg.C and oil temp sensor is no failure(P0711,P0712,P0713 or Vehicle Speed calculated by output revolution sensor >= 66 km/h) | <pre>>>10sec (>=2.5sec))</pre> | | |
| | | | | | Selector position switch | Defined | _ | |
| | | | | | Vehicle apod | | _ | |
| | | | | | Shift solenoid (S1: P0973,P0974 S2: P0976,P0977 S3: P0979,P0980) Selector position switch(P0705) | Not fail | | |
| Selector position switch | P0705 | circuit continuity | Pattern of the switches | illegal pattern | DS_Active_EG_V | TRUE | 0.5sec | 1D.C. |
| | | | | | Emergency mode | No | | |
| Transmission oil temperature sensor | P0712 | circuit continuity | Input A/D value | <10 | DS_ACTIVE_EG_V Emergency mode | TRUE No | 5min | 1D.C. |
| (GND SHOIL) | D0712 | oirquit continuity | Input A/D volue | . 1000 | | TRUE | 12000 | 10.0 |
| tomporaturo concor | FU/13 | | input A/D value | >=1000 | DS_ACTIVE_EG_V | No | 12500 | 10.0. |
| (Open JR Short) | | | | | Enlegency mode | D 2 2 1 range defined | - | |
| (Open, +b Short) | | | | | Output revolution | b, 5, 2, 1 lange defined | - | |
| | | | | | Output revolution Output revolution sensor(P0722) | Not fail | | |
| | | | | | Selector position switch(P0705) | | | |
| Transmission oil | P0711 | functional check | Criteria flag | TRUE | DS_Active_EG_V | TRUE | 10min | 1D.C. |
| temperature sensor | | | | (Criteria timer shall keep | Emergency mode | No | | |
| (Stuck) | | | 1. INITIAL status Criteria flag = FALSE OT_base = Init Oil temperature OT_base_AD = Init Oil A/D value Goto "WAITING" status 2. WAITING status Criteria flag = FALSE OT = Oil temperature OT AD = Oil 4/D value | at HOLD status) | Oil temperature sensor AD | >=10,<943 | | |

| OT_base = Init Oil temperature | | | | | |
|--|--|---|--|---|--|
| OT_base_AD = Init Oil A/D value If cond1 is satisfied, goto "CRITERIA" status | | | | | |
| 3. CRITERIA status Criteria flag = TRUE If cond5 is satisfied, goto "WAITING" status If cond2 is satisfied, goto "NORMAL" status If cond3 is satisfied, goto "HOLD" status | | | | | |
| 4. NORMAL status Criteria flag = FALSE OT = Oil Temperature OT_AD = Oil A/D value OT_base = Init Oil Temperature OT_base_AD = Init Oil A/D value If cond5 is satisfied, goto "WAITING" status If cond1 is satisfied, goto "CRITERIA" status | | | | | |
| 5. HOLD status Criteria flag = FALSE | | | | | |
| If cond5 is satisfied, goto "WAITING" status If cond4 is satisfied, goto "CRITERIA"status | | | | | |
| Cond1: (OT < 20deg.C or OT_base < 20deg.C) AND Range!=(P,R or N) AND Vehicle speed >= 40km/h at once (if state Vehicle speed parameter is reseted) Cond2: LOT AD - input A/D value L > 10* OR | *When A/D value +/- 10 | | | | |
| OT_base_AD - input A/D value >10* Cond3: Range = (P,R or N) Cond4: Range !=(P,R or N) | changes, it is about +/- 1 deg C, depends on temperature, transfer function is non-linear. | | | | |
| Vehicle speed >= 40km/h at once Cond5: Window condition is not satisfied | | | | | |
| ntinuity Battery voltage | < 9V | Input revolution(P0717) | >=800 rpm | 1time | 1D.C. |
| ntinuity Battery voltage | > 18V | Input revolution(P0717) | >=800 rpm | 1time | 1D.C. |
| I check The relationship between NC1 cycle time (A/T input | >=2.5sec | DS_ACTIVE_EG_V | TRUE | 2times | 1D.C. |
| and SP cycle time (A/T output signal) is not correct | | Emergency mode | No | | |
| (Error detection condition is the difference of gear ratio | | Throttle | >=10% | | |
| more than equal to 10%) | | Output revolution | >=500rpm | | |
| | | Selector position switch | D, 3, 2, 1 range defined | | |
| | | Time offer geer colector change | | | |
| | | Time after gear selector change | >=/SEC | | |
| | | Oil temporature | >=3580 | 1 | |
| | | Shift solenoid | Not fail | | |
| | | (S1: P0973,P0974 S2: P0976,P0977 S3: P0979,P0980) | | | |
| | OT_base_AD = Init Oil A/D value If cond1 is satisfied, goto "CRITERIA" status 3. CRITERIA status Criteria flag = TRUE If cond3 is satisfied, goto "NORMAL" status If cond3 is satisfied, goto "NORMAL" status If cond3 is satisfied, goto "HOLD" status 4. NORMAL status Criteria flag = FALSE OT = Oil Temperature OT_base_AD = Init Oil A/D value If cond5 is satisfied, goto "CRITERIA" status If cond1 is satisfied, goto "CRITERIA" status If cond1 is satisfied, goto "CRITERIA" status If cond1 is satisfied, goto "CRITERIA" status If cond4 is satisfied, goto "CRITERIA" status Cond1: (OT < 20deg.C or OT_base < 20deg.C) AND Rangel=(P,R or N) AND Vehicle speed >= 40km/h at once (if state Vehicle speed parameter is reseted) Cond2: OT_AD - input A/D value > 10" OR OT_base_AD - input A/D value > 10" OR OT_base_AD - input A/D value > 10" Cond3: Range != (P,R or N) Cond4: Range != (P,R or N) Vehicle speed >= 40km/h at once Cond5: Window condition is not satisfied ttinuity Battery voltage ttinuity Battery voltage ttinuity Battery voltage ttinuity Battery voltage ttinuity Battery voltage | OT_base_AD = Init OI /AD value If cond1 is satisfied, goto "CRITERIA" status 3. CRITERIA status Criteria flag = TRUE If cond3 is satisfied, goto "WAITING" status If cond3 is satisfied, goto "CRITERIA" status 4. NORMAL status Criteria flag = FALSE OT = OII Temperature OT_base_AD = Init OII AD value To_base_AD = Init OII AD value If cond3 is satisfied, goto "CRITERIA" status If cond1 is satisfied, goto "CRITERIA" status If cond5 is satisfied, goto "CRITERIA" status If cond5 is satisfied, goto "CRITERIA" status If cond5 is satisfied, goto "CRITERIA" status If cond6 is satisfied, goto "CRITERIA" status Criteria flag = FALSE If cond5 is satisfied, goto "CRITERIA" status If cond6 is satisfied, goto "CRITERIA" status If cond6 is goto = 40km/h at once (if state Vehicle speed parameter is reseted) Cond2: OT_AD - input AD value > 10* Cond3: Range = (P,R or N) Range = (P,R or N) Range = (P,R or N) Vehicle speed >= 40km/h at once Cond6: Window condition is not satisfied timuity "When A/D value +/- 10 changes, it is about +/- 10 | OT_base_AD bit Oil AD value If cond1 is satisfied, got "CRTERIA" status 3. CRITERIA status Criteria flag = TRUE If cond2 is satisfied, got "WATING" status If cond2 is satisfied, got "WATING" status If cond2 is satisfied, got "WATING" status If cond2 is satisfied, got "HOLD" status 4. NORMAL status Criteria flag = FALSE OT_base_AD = Init Oil AD value Criteria flag = FALSE If cond5 is satisfied, goto "WATING" status If cond5 is satisfied, goto "CRITERIA" status Cond1: (OT_base_AD = Init AD value > 10° Cond2: I OT_AD = Init AD value > 10° Cond3: Range = (P, R or N) Cond4: Range = (P, R or N) Cond4: Range = IrP, R or N) Cond4: Window condition is not satisfied Window condition is not satisfied Window condition is not satisfied Window condition is the differen | OT_base, AD = Init OLAD value If conditis autilities, point WAITING* status If conditis statistics, point WAITING* status If conditis autilities, point CATERIA* status If conditis Range IC/R ar N) Vehicle speed >= 40kmh at cone Conditis If conditis If conditis not statisfied If the PAR area in the informance of gear ratio If the PAR area in the informance of gear ratio If the PAR area information in the difference of gear ratio Stelectrip pointies in the difference of gear ratio Stelectrip pointies in the difference of gear ratio If the PAR area information If the PAR area informating and in the condition in the informance of gear ratio If the PAR | of T_base_AD = Init Ol AD value of Control is satisfied, goor CRITERIA statue a CRITERIA statue Control is satisfied, goor VATING' status if conds is satisfied, goor VATING' status Check is assidied, goor VATING' status if conds is satisfied, goor VATING' status Check is assidied, goor VATING' status if conds is satisfied, goor VATING' status Check is assidied, goor VATING' status of LAB - OLAD value Of T_Dase_AD - Init OLAD value of T_B = OLAD value Of Treporture of Treporture Of Treporture of Treporture Of Treporture of Treporture Of Treporture of Treporture Of Treporture of Treporture |

| Check | Fault Code Monitoring Strategy Malfunction Criteria Threshold Value Secondary Parameters | | Secondary Parameters | Enable Conditions | Time Required | MIL Illumination | | |
|--------------------------|--|-------------------------|---|----------------------------|---|--------------------------|----------|-------|
| | | | | | Output speed sensor(P0722) | | | |
| | | | | | Input revolution(P0717) | | | |
| | | | | | Selector position switch(P0705) | | | |
| | | | | | Oil temperature sensor | | | |
| | | | | | (P0711, P0712, P0713) | | | |
| Shift Mechanism | P0780 | functional check | Unexpected downshift | Occurrence | DS_ACTIVE_V | TRUE | 1280msec | 1D.C. |
| | | | | | Emergency mode | No | | |
| | | | | | Selector position switch | D, 3, 2, 1 range defined | | |
| | | | | | During shift | No | | |
| | | | | | Neutral control | No | | |
| | | | | | Time after gear selector change | >=3sec | | |
| | | | | | Shift solenoid | Not fail | | |
| | | | | | (S1: P0973,P0974 | | | |
| | | | | | S2: P0976,P0977 | | | |
| | | | | | S3: P0979, P0980) | | | |
| | | | | | Selector position switch(P0705) | | | |
| | | | | | Time after gear selector change from | >=10sec | | |
| | | | | | P R or N range to others | | | |
| | | | | | (at oil temp >=20deg C and oil temp | (>=2 5sec) | | |
| | | | | | sensor is no failure (P0711 P0712 P0713 | () = 2.0000) | | |
| | | | | | or Vehicle Speed calculated by output | /) | | |
| | | | | | rovolution sonsor $> = 66 \text{ km/h}$ | | | |
| Newtral Ocastral | D0704 | for a the set of a set. | TONA data ata A/T inggat any inggana dang (A/T inggat any | 0.0 | | | 14:00 0 | 10.0 |
| | PUT9A | functional check | I CM detects A/T input rev. is more than (A/T input rev. | >=0.3 sec | DS_ACTIVE_EG_V | | Tume | ID.C. |
| (Engine flare at C1 | | | apply start + A/T output rev. * gear ratio + 400rpm) | | Emergency mode | INO | | |
| appiy) | | | | | During apply control | Yes | | |
| | | | | | Oil temperature sensor | >=10°C | _ | |
| | | | | | Selector position switch | D, 3, 2, 1 range defined | | |
| | | | | | Pressure control solenoid value | >=3.0Kg/cm | | |
| Neutral Control | P0762 | functional check | A/T Input revolution is more than | >=10sec | DS_ACTIVE_EG_V | TRUE | 3times | 1D.C. |
| (Engine flare at neutral | | | (A/T output * gear ratio + 500 rpm.) | | Emergency mode | No | | 1 |
| control OFF) | | | | | Neutral control | No | | |
| | | | | | All of the following conditions are satisfied | | | |
| | | | | | after output revolution >= 250 rpm | | | |
| | | | | | During shift | No | | |
| | | | | | Selector position switch | D, 3, 2, 1 range defined | | |
| | | | | | Oil temperature | >=10°C | | |
| | | | | | Output revolution | <250rpm | | |
| | | | | | Engine revolution | >0rpm | | |
| Bus Off counter over ru | U2104 | Check the bus | If MPU receive "BUS OFF" state from CAN controller | | DS_ACTIVE_V | TRUE | 1time | 1D.C. |
| | | condition | | | Time after IG ON | >=3sec | | |
| | | | | - | | | | |
| | | | | | | | | |
| | | | | | | | | |
| Lost communication | U0100 | Check the CAN | If TCM cannot detect frame of GENERAL STATUS ECM | >=4sec | DS_ACTIVE_V | TRUE | 1time | 1D.C. |
| with ECM | | signal from ECM | (Node ID: \$300) | | Time after IG ON | >=3sec | | |
| | | - | | | InRpm or EgRpm | >=400rpm | | |
| Flash ROM | P0601 | Check sum | To detect that the value of checksum calculations | Difference at stored value | - | - | 2times | 1D.C. |
| | | (Only 1time at IG ON) | executed after IG ON. | | | | | _ |
| | | (, | If there are a differences from the correct checksum | | | | | |
| | | | value stored in FLASH ROM the second calculation is | | | | | |
| | | | made. | | | | | |
| Non volatile memory | P0603 | Check sum | To detect calculated checksum in RAM is different from | Difference at stored value | - | - | 1time | 1D C |
| (EEPROM) | | (Only 1time at IG ON) | checksum value in EEPROM | | | | | |
| | | | TCM has two areas (main and sub) for FEPROM | | | | | |
| | | | This failure is detected when both areas are wrong | | | | | |
| Random accoss | | | The familie is detected when both areas are willing. | | <u> </u> | | | |
| memory | P0604 | Check the write data | To detect different value between write and read | - | - | - | 1time | 1D.C. |

| Che | ck | Fault Code | Monitoring Strategy | Malfunction Criteria | Threshold Value | Secondary Parameters | Enable Conditions | Time Required | MIL Illumination |
|-----|----|------------|-----------------------|--|-----------------|----------------------|-------------------|---------------|------------------|
| (RA | M) | | (Only 1time at IG ON) | (Step1 and Step2, Step3 and Step4) while TCM checks all RAM from step 1 to step 4 in initialize routine. Step 1. TCU writes 55(hex) data in the RAM. Step 2. TCU reads 55(hex) data in the RAM. Step 3. TCU writes AA(hex) data in the RAM. Step 4. I CU reads AA(hex) data in the RAM. | | | | | |

Notes

1. Failure detection starts when start condition for failure detection (condition 1) is fulfilled for 2.0 sec continuously (DS_Active_EG_V = TRUE)

2. All failure detection quits when permission condition for failure detection (condition 2) is not fulfilled (DS_Active_EG_V = FALSE)

3. Failure detection for CAN signal starts when start condition for failure detection (condition 1 without engine revolution condition) is fulfilled for 2.0 sec continuously (DS_Active_V = TRUE)

4. Failure detection for CAN signal quits when permission condition for failure detection (condition 2 without engine revolution condition) is not fulfiller (DS_Active_V = FALSE)

5. However, failure detection for IG voltage operates regardless the following conditions

Start condition for failure detection (condition 1)

| Ignition ON | and |
|---|---------|
| 10.2 V < Battery voltage < 15.5 V | and |
| Not in service mode (*1) | and |
| Reading non volatile memory finish | and |
| Engine revolution > 400rpm and no failure detection | on (*2) |

Permission condition for failure detection (condition 2)

| Ignition ON | and |
|--|-----|
| 9.0 V < Battery voltage < 16.5 V | and |
| Not in service mode (*1) | and |
| Engine revolution > 400rpm and no failure detection (*2) | |

*1: Service mode: Diagnostic service mode (ClearDiagnosticInformation, InputOutputControl, DisableNormalMessageTransmission).

TCU will prevent the failure detection when TCU will prevent the miss detection during InputOutputControl function. Because the CAN signal is not transmitted, the failure detection cannot be done

*2: Not in "Engine speed signal"failure(P0727) Not in "Bus off" failure(U2104) Not in "Lost Communicationwith ECM" failure(U0100)

*3: MAP_A

| turbine rev[rpm] | 1000 | 2000 | 3000 | 4000 | 5000 | 6000 |
|-------------------|------|------|------|------|------|------|
| engine torque[Nm] | 47 | 47 | 50 | 65 | 65 | 65 |